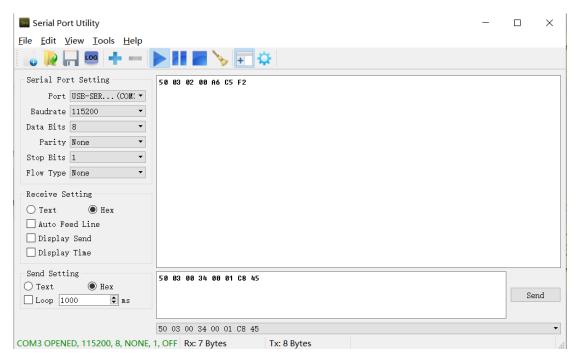


1 WT53R-485 Datasheet

1.1 Serial port mode description

The sensor returns data as shown below:



Example: d: 490mm State: 7, No Update

d: 490mm means measuring distance

State: 7, No Update indicates the status bit of the measurement data



Modbus protocol description

The sensor adopts the industry standard Modbus protocol, and the specific read and write format is as follows:

Modbus communication, the command number is divided into two kinds of read command and write command, 0x03 (read command) reads the corresponding register data, 0x06 (write command) writes data to the corresponding register.

PC software sends data frame

ID	Comman	Register	Register	Read	Low bit	CRC	CRC
	d number	address	address	length	of read	check	check
		high	low	high	length	high bit	low bit
ID	CMD	RegH	RegL	LenH	LenL	CRCH	CRCL

Example: The module address is 0x50 (default), the read command is 0x03, the register 0x34 (measurement distance), the length is one bit.

Command: 50 03 00 34 00 01 C8 45

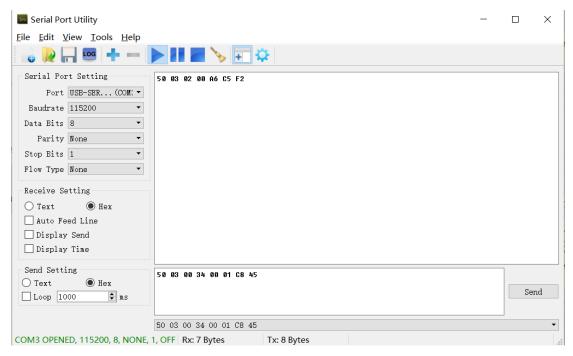
Module reply frame

ID	Comman	Data	Data bit 1	Data bit 2	CRC	CRC
	d number	length			check	check
					high bi	low bit
ID	CMD	LenH	DataH	DataL	 CRCH	CRCL

Example: The module address is 0x00, the read command is 0x03, and the length is 2 bits. replied as below

Command: 50 03 02 00 1C 44 41

Example: Read the measured distance, as shown in the figure below:



Send command: 50 03 00 34 00 01 c8 45



Accepted data: 50 03 02 07 0B 06 7F

Data analysis 0x50 is Modbus address, 0x03 read command, 0x02 data length, 0x07 0x0B measurement data corresponding to 0x070B is decimal 1803, measuring distance is 18036mm, 0x06 0x7F is CRC check bit.

1.2 Modbus register document

Register name	Register address	Send format	Explanation
System recovery	0x00	MODADDR 06 00 00 00 01	Write 0x01, the sensor restores
		CRCH CRCL	the default setting
Return rate	0x03	MODADDR 06 00 03 00 00	Write 0x00, the return speed is
		CRCH CRCL	0.1Hz
		MODADDR 06 00 03 00 01	Write 0x01, the return speed is
		CRCH CRCL	0.2Hz
		MODADDR 06 00 03 00 02	Write 0x02, the return speed is
		CRCH CRCL	0.5Hz
		MODADDR 06 00 03 00 03	Write 0x03, the return speed is
		CRCH CRCL	1Hz
		MODADDR 06 00 03 00 04	Write 0x04, the return speed is
		CRCH CRCL	2Hz
		MODADDR 06 00 03 00 05	Write 0x05, the return speed is
		CRCH CRCL	5Hz
		MODADDR 06 00 03 00 06	Write 0x06, the return speed is
		CRCH CRCL	10Hz
		MODADDR 06 00 03 00 07	Write 0x07, the return speed is
		CRCH CRCL	20Hz
		MODADDR 06 00 03 00 08	Write 0x08, the return speed is
		CRCH CRCL	50Hz
Baud rate	0x04	MODADDR 06 00 04 00 00	Write 0x00, baud rate 2400
setting		CRCH CRCL	
		MODADDR 06 00 04 00 01	Write 0x01, baud rate 4800
		CRCH CRCL	
		MODADDR 06 00 04 00 02	Write 0x02, the baud rate is
		CRCH CRCL	9600
		MODADDR 06 00 04 00 03	Write 0x03, the baud rate is
		CRCH CRCL	19200
		MODADDR 06 00 04 00 04	Write 0x04, the baud rate is
		CRCH CRCL	38400
		MODADDR 06 00 04 00 05	Write 0x05, baud rate 57600
		CRCH CRCL	



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		MODADDR 06 00 04 00 06	Write 0x06, baud rate 115200
		CRCH CRCL	
		MODADDR 06 00 04 00 07	Write 0x07, baud rate 230400
		CRCH CRCL	
		MODADDR 06 00 04 00 08	Write 0x08, baud rate 460800
		CRCH CRCL	
		MODADDR 06 00 04 00 09	Write 0x09, the baud rate is
		CRCH CRCL	921600
WT53R timing	0x07	MODADDR 06 00 07	TIMEBUDGET:
preset time (it is		TIMEBUDGETH	20-1000 milliseconds can be
not			changed to 0x0014-0x03e8
recommended to			
modify the			
default value			
200)			
WT53R	0x08	MODADDR 06 00 08	PERIOD: 1-1000 milliseconds
measurement		PERIODH PERIODL CRCH	can be changed
interval (it is not		CRCL	0x0001-0x03e8
recommended to			
modify the			
default value of			
50)			
ID setting	0x1A	MODADDR 06 00 1a 00	Write 0x00~0xFE
		MODADDRL CRCH CRCL	
Measurement	0x34	MODADDR 03 00 34 00 01	Read, distance high 8 bits and
data		CRCH CRCL	distance low 8 bits
Output state	0x35	MODADDR 03 00 35 00 01	Read: 0x07, sensor No Update
		CRCH CRCL	Read: 0x00, sensor Range
			Valid
			Read: 0x01, sensor Sigma Fail
			Read: 0x02, sensor Signal Fail
			Read: 0x03, sensor Min Range
			Fail
			Read: 0x04, sensor Phase Fail
			Read: 0x05, Sensor Hardware
			Fail
Measurement	0x36	MODADDR 06 00 36 00 00	Write 0x00, short distance
mode		CRCH CRCL	(Up to 1.3m, better
			environmental immunity)
		MODADDR 06 00 36 00 01	Write 0x01, middle distance
		CRCH CRCL	(Up to 3 meters)
		MODADDR 06 00 36 00 02	Write 0x02, long distance
		CRCH CRCL	mode
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			(Up to 4 meters)
Calibration	0x37	MODADDR 06 00 37 00 04	Write 0x04, enter the
Mode		CRCH CRCL	calibration state
		MODADDR 03 00 37 00 01	Read: 0x01, start calibration
		CRCH CRCL	Read: 0x02, calibration failed
			Read: 0x03, calibration is
			complete
System mode	0x38	MODADDR 06 00 38 00 00	Write 0x00, sensor normal
		CRCH CRCL	mode, automatic return
		MODADDR 06 00 38 00 01	
		CRCH CRCL	

2 Application

Drone Robot







Smart device

